

Strong normalisation in the full simple theory of types

Categorical Logic and Constructive Mathematics



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Full simple theory of types

Assume the separated variables convention and suppose to fix a set of *type constants*. The full simple theory of types is then

$$\begin{array}{c}
 \frac{}{x : T} \quad \frac{t : T_2 \quad x : T_1}{\lambda x : T_1 t : T_1 \rightarrow T_2} \quad \frac{t : T_1 \rightarrow T \quad t_1 : T_1}{t \cdot t_1 : T} \\
 \frac{t_1 : T_1 \quad t_2 : T_2}{(t_1, t_2) : T_1 \times T_2} \quad \frac{t : T_1 \times T_2}{t \cdot \pi_1 : T_1} \quad \frac{t : T_1 \times T_2}{t \cdot \pi_2 : T_2} \\
 \frac{t : T_1}{\text{inl}_{T_2} t : T_1 + T_2} \quad \frac{t : T_2}{\text{inr}_{T_1} t : T_1 + T_2} \\
 \frac{t : T_1 + T_2 \quad a : T \quad b : T}{t \cdot \delta(x_0 : T_1.a, x_1 : T_2.b) : T} \quad \frac{t : \mathbf{0}}{t \cdot \phi_T : T}
 \end{array}$$

where x, x_0, x_1 are variables, and λ and δ bind x and x_0, x_1 respectively.

Elimination-oriented syntax

Eliminator: an element R such that $t \cdot R$ is a term.

May be a term a , π_1 , π_2 , ϕ_T , or $\delta(x_0 : A, x_1 : B, b)$.

Vector notation: \vec{r} denotes a list r_1, \dots, r_n of terms; \vec{R} denotes a list R_1, \dots, R_n of eliminators.

Vector application: $t \cdot \vec{R}$ is t when $n = 0$, and $(t \cdot \vec{S}) \cdot R_n$ with $\vec{S} = R_1, \dots, R_{n-1}$ when $n > 0$.

Vector relations: $\vec{R} \in X$ is a shorthand for $R_1 \in X, \dots, R_n \in X$, where the π_1 , π_2 , and ϕ_T eliminators vacuously satisfy membership, and $\delta(x_0, a, x_1, b) \in X$ means $a \in X$ and $b \in X$. Other relations, e.g., $x \notin \text{FV}(\vec{R})$, are similarly defined.

Reductions

\triangleright_1 , *one-step reduction*, is the minimal congruence containing \blacktriangleright .

\triangleright , *reduction*, is the reflexive and transitive closure of \triangleright_1 .

Computation contractions:

- $(\lambda x:A.b) \cdot a \blacktriangleright b[x/a]$
- $(a,b) \cdot \pi_1 \blacktriangleright a \quad (a,b) \cdot \pi_2 \blacktriangleright b$
- $(\text{inl}_B a) \cdot \delta(x:A.b, y:B.c) \blacktriangleright b[x/a]$ with $x \notin \text{FV}(a)$
 $(\text{inr}_A a) \cdot \delta(x:A.b, y:B.c) \blacktriangleright c[y/a]$ with $y \notin \text{FV}(a)$
renaming the bounded variables if needed

Uniqueness contractions:

- $\lambda x:A.a \cdot x \blacktriangleright a$ where $x \notin \text{FV}(a)$
- $(a \cdot \pi_1, a \cdot \pi_2) \blacktriangleright a$
- $a \cdot \delta(x:A.\text{inl}_B x, y:B.\text{inr}_A y) \blacktriangleright a$
- $a \cdot \phi_0 \blacktriangleright a$

Reductions

Permutation contractions:

- $a \cdot \phi_{A \times B} \blacktriangleright (a \cdot \phi_A, a \cdot \phi_B)$
- $a \cdot \phi_{A \rightarrow B} \blacktriangleright \lambda x : A. a \cdot \phi_B$ with $x \notin \text{FV}(a)$
- $a \cdot \phi_{A+B} \blacktriangleright \text{inl}_B(a \cdot \phi_A)$
- if $r \cdot \delta(x : A. a, y : B. b) : C \times D$ then

$$r \cdot \delta(x : A. a, y : B. b) \blacktriangleright (r \cdot \delta(x : A. a \cdot \pi_1, y : B. b \cdot \pi_1), \\ r \cdot \delta(x : A. a \cdot \pi_2, y : B. b \cdot \pi_2))$$

- if $r \cdot \delta(x : A. a, y : B. b) : C \rightarrow D$ and $z \notin \{x, y\} \cup \text{FV}(r \cdot \delta(x : A. a, y : B. b))$ then

$$r \cdot \delta(x : A. a, y : B. b) \blacktriangleright \lambda z : C. r \cdot \delta(x : A. a \cdot z, y : B. b \cdot z)$$

- if $x \notin \text{FV}(c)$ and $y \notin \text{FV}(d)$ then

$$(r \cdot \delta(x : A. a, y : B. b)) \cdot \delta(z : C. c, w : D. d) \\ \blacktriangleright r \cdot \delta(x : A. a \cdot \delta(z : C. c, w : D. d), y : B. b \cdot \delta(z : C. c, w : D. d))$$

Strongly normalisable

A term t is *strongly normalisable* (sn) if (α) there is a bound $m \in \mathbb{N}$ to the length of every reduction sequence starting from t .

Equivalently, a term t is strongly normalisable when (β) every term r such that $t \triangleright_1 r$ is strongly normalisable.

A theory of types is strongly normalisable when every term which can be typed in it, is strongly normalisable.

$[(\alpha)$ and (β) are induction principles]

Naive strong normalisation

Lemma 2.1

- $\lambda x:A a$ is sn iff a is sn
- (a, b) is sn iff a and b are sn
- $\text{inl}_T a$ is sn iff a is sn
- $\text{inr}_T a$ is sn iff a is sn
- $\pi_1 a$ is sn iff a is sn
- $\pi_2 a$ is sn iff a is sn
- $a \cdot \phi_T$ is sn iff a is sn

Lemma 2.2

If $a[x/b]$ is sn, so is a .

Naive strong normalisation

Lemma 2.3

- If $a : A \rightarrow T$ is sn and $x : A$ is a variable such that $x \notin \text{FV}(a)$, then $a \cdot x$ is sn
- If $a \cdot b$ is sn, so are a and b

Lemma 2.4

- If t , f , and g are sn, and t is neither a δ -term nor an injection, then $t \cdot \delta(u.f, v.g)$ is sn.
- If $e_1 \cdot \delta(x.e_2, y.e_3)$ is sn then e_i is sn

The proofs of these lemmata are straightforward inductions on one-step reductions or the length of reductions, possibly augmented by an external induction on the types of whole terms.

[from now on, these lemmata are taken for granted]

The set **SN**

SN is the minimal set of typable terms closed by the rules in the following.

We claim that:

- if $t \in \mathbf{SN}$ then t is sn
- if $t : T$ is term, then $t \in \mathbf{SN}$

Strong normalisation is an immediate consequence.

The set **SN**

$$\begin{array}{c}
 \frac{\vec{R} \in \mathbf{SN}}{x\vec{R} \in \mathbf{SN}} (V_1) \quad \frac{x\vec{R} \in \mathbf{SN} \quad a:T \in \mathbf{SN} \quad b:T \in \mathbf{SN}}{x\vec{R}\delta(y.a,z.b) \in \mathbf{SN}} (V_2) \\
 \\
 \frac{a \in \mathbf{SN}}{\lambda x:T a \in \mathbf{SN}} (\lambda) \quad \frac{a \in \mathbf{SN} \quad b \in \mathbf{SN}}{(a,b) \in \mathbf{SN}} (p) \quad \frac{a \in \mathbf{SN}}{\text{inl}_T a \in \mathbf{SN}} (i_1) \quad \frac{a \in \mathbf{SN}}{\text{inr}_T a \in \mathbf{SN}} (i_2) \\
 \\
 \frac{(a[x/b])\vec{D} \in \mathbf{SN} \quad b \in \mathbf{SN}}{(\lambda x:T a)b\vec{D} \in \mathbf{SN}} (\beta) \\
 \\
 \frac{a\vec{D} \in \mathbf{SN} \quad b \in \mathbf{SN}}{(a,b)\pi_1\vec{D} \in \mathbf{SN}} (\pi_1) \quad \frac{a \in \mathbf{SN} \quad b\vec{D} \in \mathbf{SN}}{(a,b)\pi_2\vec{D} \in \mathbf{SN}} (\pi_2)
 \end{array}$$

- In the rules, \vec{R} is a list of eliminators containing no δ 's and ϕ 's.
Oppositely \vec{D} is a generic, unconstrained list of eliminators.
- In (V_2) the type T is required to be either atomic or a sum.
- x is a variable.

The set **SN**

$$\frac{(b[x/a])\vec{D} \in \mathbf{SN} \quad a \in \mathbf{SN} \quad b\vec{D} \in \mathbf{SN} \quad c\vec{D} \in \mathbf{SN}}{(\text{inl}_B a)\delta(x.b, y.c)\vec{D} \in \mathbf{SN}}_{(\delta_1)}$$

$$\frac{(c[x/a])\vec{D} \in \mathbf{SN} \quad a \in \mathbf{SN} \quad b\vec{D} \in \mathbf{SN} \quad c\vec{D} \in \mathbf{SN}}{(\text{inr}_A a)\delta(x.b, y.c)\vec{D} \in \mathbf{SN}}_{(\delta_2)}$$

$$\frac{(a \cdot \delta(y.b \cdot \pi_1, z.c \cdot \pi_1), a \cdot \delta(y.b \cdot \pi_2, z.c \cdot \pi_2))\vec{D} \in \mathbf{SN}}{a \cdot \delta(y.b, z.c)\vec{D} \in \mathbf{SN}}_{(\delta_\times)}$$

$$\frac{(\lambda u : A a \cdot \delta(y.b \cdot u, z.c \cdot u))\vec{D} \in \mathbf{SN}}{a \cdot \delta(y.b, z.c)\vec{D} \in \mathbf{SN}}_{(\delta_-)}$$

$$\frac{a \cdot \delta(y.b \cdot \delta(u.f, v.g), z.c \cdot \delta(u.f, v.g))\vec{D} \in \mathbf{SN}}{a \cdot \delta(y.b, z.c)\delta(u.f, v.g)\vec{D} \in \mathbf{SN}}_{(\delta_+)}$$

The set **SN**

$$\begin{array}{c}
 \frac{a \in \mathbf{SN}}{a \cdot \phi_T \in \mathbf{SN}} (\phi_a) \quad \frac{(a \cdot \phi_A, a \cdot \phi_B) \vec{D} \in \mathbf{SN}}{a\phi_{A \times B} \vec{D} \in \mathbf{SN}} (\phi_{\times}) \\
 \frac{(\lambda x : A \ a \cdot \phi_B) \vec{D} \in \mathbf{SN}}{a\phi_{A \rightarrow B} \vec{D} \in \mathbf{SN}} (\phi_{\rightarrow}) \quad \frac{(\text{inl}_B (a \cdot \phi_A)) \vec{D} \in \mathbf{SN}}{a\phi_{A+B} \vec{D} \in \mathbf{SN}} (\phi_{+})
 \end{array}$$

- In (δ_{\times}) the type of $a \cdot \delta(y.b, z.c)$ is a product $A \times B$.
- In (δ_{\rightarrow}) the type of $a \cdot \delta(y.b, z.c)$ is a function space $A \rightarrow B$.
- In (ϕ_a) the type T is required to be atomic.
- In all the rules, the same constraints as for contractions apply on free and bounded variables.

Combinatorics of δ

Definition 4.1

To cope with nested δ -eliminators and their permutations, it is useful to define Δ_n and ∇_n :

$$\Delta_n(a, b_1, c_1, \dots, b_n, c_n) = a \cdot \delta(x_1 \cdot b_1, y_1 \cdot c_1) \cdots \delta(x_n \cdot b_n, y_n \cdot c_n)$$

and

$$\begin{aligned} \nabla_n(a, b_1, c_1, \dots, b_n, c_n) = & a \cdot \delta(x_1 \cdot \nabla_{n-1}(b_1, b_2, c_2, \dots, b_n, c_n), \\ & y_1 \cdot \nabla_{n-1}(c_1, b_2, c_2, \dots, b_n, c_n)) \end{aligned}$$

with $\Delta_0(a) = a = \nabla_0(a)$.

Combinatorics of δ

Lemma 4.2

For every n and for every $a, b_1, \dots, b_n, c_1, \dots, c_n$ sn terms,
 $\Delta_n(a, b_1, c_1, \dots, b_n, c_n)$ is sn iff $\nabla_n(a, b_1, c_1, \dots, b_n, c_n)$ is so.

Proof. (i)

Suppose $\Delta_n(\dots)$ is sn. Since it reduces to $\nabla_n(\dots)$, $\nabla_n(\dots)$ is sn, too.

Conversely, for every n and for every $a, b_1, \dots, b_n, c_1, \dots, c_n$ sn, if
 $\nabla_n(a, b_1, c_1, \dots, b_n, c_n) : T$ is sn and $\Delta_n(a, b_1, c_1, \dots, b_n, c_n) \triangleright_1 r$ then r is sn.
The proof is by induction on

$$(n, T, \text{maxred}(a) + \sum_{j=1}^n \text{maxred}(b_j) + \sum_{j=1}^n \text{maxred}(c_j))$$

lexicographically ordered.



[$\text{maxred}(t)$ is the length of the longest reduction sequence starting from t]

Combinatorics of δ

↪ Proof. (ii)

Considering the possible one-step reductions:

- $r = \Delta_n(a', b_1, c_1, \dots, b_n, c_n)$ and $a \triangleright_1 a'$. Since n and T are unchanged in r , but $\text{maxred}(a') < \text{maxred}(a)$, r is sn by IH. Likewise for $b_i \triangleright_1 b'$ or $c_i \triangleright_1 c'$.
- $r = \Delta_{n-1}(b_1[x/a'], b_2, c_2, \dots, b_n, c_n)$ and $a = \text{inl}_{C_1} a'$. Since

$$\nabla_n(a, b_1, c_1, \dots, b_n, c_n) \triangleright_1 \nabla_{n-1}(b_1[x/a'], b_2, c_2, \dots, b_n, c_n)$$

and the lhs side is sn, so is the rhs side, thus the subterm $b_1[x/a']$ is sn. Then r is sn by IH. Similarly when $a = \text{inr}_{B_1} a'$.

- $r = \Delta_{n-1}(a, b_1, c_1, \dots, b_{i-1}, c_{i-1}, b_{i+1}, c_{i+1}, \dots, b_n, c_n)$ and $b_i = \text{inl}_{C_{i+1}} x_i$, $c_i = \text{inr}_{B_{i+1}} y_i$. Thus r is sn by IH.

↪

Combinatorics of δ

↪ Proof. (iii)

- $T = C \times D$ and

$$r = (\Delta_n(a, b_1, c_1, \dots, b_{n-1}, c_{n-1}, b_n \cdot \pi_1, c_n \cdot \pi_1) : C, \\ \Delta_n(a, b_1, c_1, \dots, b_{n-1}, c_{n-1}, b_n \cdot \pi_2, c_n \cdot \pi_2) : D) .$$

Since $b_n \cdot \pi_1$, $b_n \cdot \pi_2$, $c_n \cdot \pi_1$, and $c_n \cdot \pi_2$ are sn,

$\Delta_n(a, b_1, c_1, \dots, b_{n-1}, c_{n-1}, b_n \cdot \pi_1, c_n \cdot \pi_1)$ and

$\Delta_n(a, b_1, c_1, \dots, b_{n-1}, c_{n-1}, b_n \cdot \pi_2, c_n \cdot \pi_2)$ are sn by IH, since n is the same, but their types are proper subtypes of T . Hence r is sn.

- $T = C \rightarrow D$ and $r = \lambda w : C \Delta_n(a, b_1, c_1, \dots, b_{n-1}, c_{n-1}, b_n \cdot w, c_n \cdot w)$.

Since $b_n \cdot w$ and $c_n \cdot w$ are sn

$$\Delta_n(a, b_1, c_1, \dots, b_{n-1}, c_{n-1}, b_n \cdot w, c_n \cdot w)$$

is sn by IH since its type D is a proper subtype of T . Thus r is sn.

↪

Combinatorics of δ

↪ Proof. (iv)

- r is the result of a permutation contraction on a sum type:

$$\begin{aligned} r = \Delta_{n-1}(a, b_1, c_1, \dots, b_{i-1}, c_{i-1}, \\ b_i \cdot \delta(x_{i+1} \cdot b_{i+1}, y_{i+1} \cdot c_{i+1}), \\ c_i \cdot \delta(x_{i+1} \cdot b_{i+1}, y_{i+1} \cdot c_{i+1}), \\ b_{i+2}, c_{i+2}, \dots, b_n, c_n) \end{aligned}$$

and $1 \leq i < n$. Considering $R = \nabla_{n-i}(b_i, b_{i+1}, c_{i+1}, \dots, b_n, c_n)$, this term is a subterm of $\nabla_n(a, b_1, c_1, \dots, b_n, c_n)$, which is sn by hypothesis, thus R is sn, too. Hence $\Delta_{n-i}(b_i, b_{i+1}, c_{i+1}, \dots, b_n, c_n)$ is sn by IH, so its head $b_i \cdot \delta(x_{i+1} \cdot b_{i+1}, y_{i+1} \cdot c_{i+1})$ is sn. Likewise, $c_i \cdot \delta(x_{i+1} \cdot b_{i+1}, y_{i+1} \cdot c_{i+1})$ is sn. Then r is sn by IH. □

$t \in \mathbf{SN}$ implies t sn

Theorem 4.3

$\mathbf{SN} \subseteq \{t \mid t \text{ is sn}\}.$

Proof. (i)

By induction on the generation of \mathbf{SN} : if $t \in \mathbf{SN}$ is the conclusion of a rule, it has to be shown that t is sn, assuming the premises of the rule are sn.

- (V_1) , (V_2) , (λ) , (p) , (i_1) , (i_2) , and (ϕ_a) are easy instances of the naive lemmata combined with the IH. \hookrightarrow

$t \in \mathbf{SN}$ implies t sn

↪ Proof. (ii)

- (β) Since $(a[x/b])\vec{D} \in \mathbf{SN}$ and $b \in \mathbf{SN}$, then $(a[x/b])\vec{D}$ and b are sn by IH, thus a , $a[x/b]$ and each eliminator in \vec{D} are sn. Then $(\lambda x: T a)b\vec{D}$ is sn by side induction on $|\vec{D}|$.

If $|\vec{D}| = 0$, consider $(\lambda x: T a) \cdot b \triangleright_1 r$. Then r is sn by inner induction on $\text{maxred}(a) + \text{maxred}(b)$: if $r = (\lambda x: T a') \cdot b$ and $a \triangleright_1 a'$, or $r = (\lambda x: T a) \cdot b'$ and $b \triangleright_1 b'$, then r is sn by inner IH; if $r = a[x/b]$ because of β -contraction or η -contraction then r is sn as above.

Hence, $(\lambda x: T a)b$ is sn since it reduces in one step to sn terms only. ↪

$t \in \mathbf{SN}$ implies t sn

\hookrightarrow Proof. (iii)

If $\vec{D} = \vec{E} G$ then $(\lambda x : T a) b \vec{E}$ is sn by side IH on \vec{E} .

Let $((\lambda x : T a) b \vec{E}) \cdot G \triangleright_1 r$. Then r is sn by inner induction on $\text{maxred}((\lambda x : T a) b \vec{E}) + \text{maxred}(G)$: if r is obtained reducing a component in the application, then r is sn by inner IH.

If G is a term, $G = \pi_1$, or $G = \pi_2$, no other reductions are possible. If $G = \phi_C$ then $(\lambda x : T a) b \vec{D}$ is sn, thus also r is sn.

So let G be a δ -eliminator. If $\vec{E} = \vec{F} \delta(y.F_1, z.F_2)$ and $r = (\lambda y : T a) b \vec{F} \delta(y.F_1 G, z.F_2 G)$ then

$$(a[x/b]) \vec{D} \triangleright_1 (a[x/b]) \vec{F} \delta(y.F_1 G, z.F_2 G),$$

in which the lhs is sn, thus it is so also the rhs, hence $\delta(y.F_1 G, z.F_2 G)$ is sn. Then r is sn by side IH.

If the last eliminator in \vec{E} , if any, is not a δ -eliminator, then $(\lambda x : T a) b \vec{D}$ is sn by the naive lemma on δ . Thus r is sn. \hookrightarrow

$t \in \mathbf{SN}$ implies t sn

→ Proof. (iv)

- (π_1) and (π_2) are analogous to the (β) case.
- (δ_1) is very similar to (β) . However, one more case has to be considered: when $\vec{D} = G$, G is a δ -eliminator, and $r = (\text{inl}_B a)\delta(x.b \cdot G, y.c \cdot G)$, then $b\vec{D} = b \cdot G$ and $c\vec{D} = c \cdot G$. Thus $b \cdot G$ and $c \cdot G$ are sn by main IH, so $\delta(x.b \cdot G, y.c \cdot G)$ is sn. Then r is sn by side IH.
- (δ_2) Symmetrical to the case (δ_1) .
- (δ_\times) , (δ_\rightarrow) , (ϕ_\times) , (ϕ_\emptyset) , and (ϕ_+) are, in turn, analogous to (δ_1) . →

$t \in \mathbf{SN}$ implies t sn

→ Proof. (v)

- (δ_+) It is convenient to write the conclusion as $\Delta_n(a, b_1, c_1, \dots, b_n, c_n) \vec{D} \in \mathbf{SN}$ where a is not a δ -term and \vec{D} is empty or its first element is not a δ -eliminator. Then the premise of the rule becomes, for some $1 \leq i < n$,

$$\begin{aligned} P = \Delta_{n-1}(a, b_1, c_1, \dots, b_{i-1}, c_{i-1}, \\ b_i \cdot \delta(x_{i+1}.b_{i+1}, y_{i+1}.c_{i+1}), \\ c_i \cdot \delta(x_{i+1}.b_{i+1}, y_{i+1}.c_{i+1}), \\ b_{i+2}, c_{i+2}, \dots, b_n, c_n) \vec{D} \in \mathbf{SN} \end{aligned}$$

Thus P is sn by IH. Since $P \triangleright \nabla_n(a, b_1, c_1, \dots, b_n, c_n) \vec{D}$, $\nabla_n(a, b_1, c_1, \dots, b_n, c_n) \vec{D}$ is sn. Thus $\Delta_n(a, b_1, c_1, \dots, b_n, c_n)$ is sn by the previous lemma. Hence $\Delta_n(a, b_1, c_1, \dots, b_n, c_n) \vec{D}$ is sn by induction on $|\vec{D}|$ as in the previous cases. □

SN and term formation

Theorem 5.1

The following facts hold, assuming all the terms are typable:

1. *if x is variable then $x \in \mathbf{SN}$;*
2. *if $a \in \mathbf{SN}$ then $\lambda x : T \ a \in \mathbf{SN}$;*
3. *if $a \in \mathbf{SN}$ and $b \in \mathbf{SN}$ then $(a, b) \in \mathbf{SN}$;*
4. *if $a \in \mathbf{SN}$ then $\text{inl}_T a \in \mathbf{SN}$ and $\text{inr}_T a \in \mathbf{SN}$;*
5. *if $T = A \rightarrow B$ and $e : T \in \mathbf{SN}$ then $e \cdot a \in \mathbf{SN}$ for all $a \in \mathbf{SN}$;*
6. *if $T = A \times B$ and $e : T \in \mathbf{SN}$ then $e \cdot \pi_1 \in \mathbf{SN}$ and $e \cdot \pi_2 \in \mathbf{SN}$;*
7. *if $T = A + B$ and $e : T \in \mathbf{SN}$ then $e \cdot \delta(x : A. a, y : B. b) \in \mathbf{SN}$ for all $a : C \in \mathbf{SN}$ and $b : C \in \mathbf{SN}$;*
8. *if $a \in \mathbf{SN}$ then $a \cdot \phi_T \in \mathbf{SN}$;*
9. *if $x : T$ is a variable and $e : A \in \mathbf{SN}$ then $e[x/a] \in \mathbf{SN}$ for all $a : T \in \mathbf{SN}$.*

SN and term formation

Proof. (i)

Properties (1)–(4), are instances of (V_1) , (λ) , (ρ) , (i_1) , and (i_2) .

Property (8) is proved by induction on T :

- T atomic. Then $a \cdot \phi_T \in \mathbf{SN}$ by (ϕ_a) .
- $T = A \times B$. Then $a \cdot \phi_A \in \mathbf{SN}$ and $a \cdot \phi_B \in \mathbf{SN}$ by IH on A and B . Thus $(a \cdot \phi_A, a \cdot \phi_B) \in \mathbf{SN}$ by (ρ) , hence $a \cdot \phi_T \in \mathbf{SN}$ by (ϕ_{\times}) .
- $T = A \rightarrow B$. Then $a \cdot \phi_B \in \mathbf{SN}$ by IH on B . Let $x : A \notin \text{FV}(a)$. Thus $\lambda x : A a \cdot \phi_B \in \mathbf{SN}$ by (λ) , hence $a \cdot \phi_T \in \mathbf{SN}$ by (ϕ_{\rightarrow}) .
- $T = A + B$. Then $a \cdot \phi_A \in \mathbf{SN}$ by IH on A . Thus $\text{inl}_B(a \cdot \phi_A) \in \mathbf{SN}$ by (i_1) , hence $a \cdot \phi_T \in \mathbf{SN}$ by (ϕ_+) .

↪

SN and term formation

↪ Proof. (ii)

Property (6) has to show that $e \cdot \pi_1 \in \mathbf{SN}$ and $e \cdot \pi_2 \in \mathbf{SN}$ from $e: T = A \times B \in \mathbf{SN}$. The proof is by induction on the generation of $e \in \mathbf{SN}$:

- $e = x \vec{R}$ by (V_1) , so $\vec{R} \in \mathbf{SN}$. Hence $e \cdot \pi_1 \in \mathbf{SN}$ and $e \cdot \pi_2 \in \mathbf{SN}$ by (V_1) .
- $e = (a, b)$ by (p) , so $a \in \mathbf{SN}$ and $b \in \mathbf{SN}$. Thus $e \cdot \pi_1 \in \mathbf{SN}$ by (π_1) and $e \cdot \pi_2 \in \mathbf{SN}$ by (π_2) .
- $e = (\lambda x: C b) c \vec{D}$ by (β) , so $b[x/c] \vec{D} \in \mathbf{SN}$ and $c \in \mathbf{SN}$.
Hence $b[x/c] \vec{D} \cdot \pi_1 \in \mathbf{SN}$ and $b[x/c] \vec{D} \cdot \pi_2 \in \mathbf{SN}$ by IH, thus $e \cdot \pi_1 \in \mathbf{SN}$ and $e \cdot \pi_2 \in \mathbf{SN}$ by (β) .

The cases for the rules (π_1) , (π_2) , (δ_1) , (δ_2) , (δ_\times) , (δ_\rightarrow) , (δ_+) , (ϕ_\times) , (ϕ_\rightarrow) , and (ϕ_+) are analogous. ↪

SN and term formation

→ Proof. (iii)

Two technical properties are needed to continue the proof:

- (T1) if $a \in \mathbf{SN}$ and $x \notin \text{FV}(a)$ then $a[y/x] \in \mathbf{SN}$. This property holds by an immediate induction on the generation of $a \in \mathbf{SN}$.
- (T2) if $e : A \rightarrow B \in \mathbf{SN}$ and $w \notin \text{FV}(e)$ then $e \cdot w \in \mathbf{SN}$.

Property (T2) is proved by induction on the generation of $e \in \mathbf{SN}$, observing that $w \in \mathbf{SN}$ by (V_1) on no premises:

- $e = z \vec{R}$ by (V_1) , so $\vec{R} \in \mathbf{SN}$, thus $e \cdot w \in \mathbf{SN}$ by (V_1) .
- $e = \lambda y : Ab$ by (λ) , so $b \in \mathbf{SN}$. Since $b[y/w] \in \mathbf{SN}$ by Property (T1), $e \cdot w \in \mathbf{SN}$ by (β) .
- $e = (\lambda x : Cb)c \vec{D}$ by (β) , so $b[x/c] \vec{D} \in \mathbf{SN}$ and $c \in \mathbf{SN}$. Then $b[x/c] \vec{D} \cdot w \in \mathbf{SN}$ by IH, thus $e \cdot w \in \mathbf{SN}$ by (β) .

The cases for the rules (π_1) , (π_2) , (δ_1) , (δ_2) , (δ_\times) , (δ_\rightarrow) , (δ_+) , (ϕ_\times) , (ϕ_\rightarrow) , and (ϕ_+) are similar. →

SN and term formation

↪ Proof. (iv)

Properties (5), (7) and (9) are proved together by induction on (T, e) , where T is ordered by the subtype relation, e is ordered by the generation of **SN**; as usual, pairs are lexicographically ordered.

To show (5), consider the possible ways in which $e: T \rightarrow A \in \mathbf{SN}$:

- $e = x \vec{R}$ by (V_1) , so $\vec{R} \in \mathbf{SN}$. Since $a \in \mathbf{SN}$ by hypothesis, $e \cdot a \in \mathbf{SN}$ by (V_1) .
- $e = \lambda x: A b$ by (λ) , so $b \in \mathbf{SN}$. Since $a \in \mathbf{SN}$ by hypothesis and A is a proper subtype of T , $b[x/a] \in \mathbf{SN}$ by IH, so $e \cdot a \in \mathbf{SN}$ by (β) .
- $e = (\lambda x: C b) c \vec{D}$ by (β) , so $b[x/c] \vec{D} \in \mathbf{SN}$ and $c \in \mathbf{SN}$. Since $a: A \in \mathbf{SN}$ and A is a proper subtype of $T = A \rightarrow B$, $b[x/c] \vec{D} \cdot a \in \mathbf{SN}$ by IH, thus $e \cdot a \in \mathbf{SN}$ by (β) .

The cases for the rules (π_1) , (π_2) , (δ_1) , (δ_2) , (δ_\times) , (δ_\rightarrow) , (δ_+) , (ϕ_\times) , (ϕ_\rightarrow) , and (ϕ_+) are similar.

↪

SN and term formation

→ Proof. (v)

Property (7) is proved using the same technique. It has to be shown that $e \cdot \delta(x.a, y.b) : C \in \mathbf{SN}$ from $e : T = A + B$ for all $a, b \in \mathbf{SN}$:

- $e = z \vec{R}$ by (V_1) . By side induction on the type C :
 - if C is either atomic or a sum, then $e \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by (V_2) .
 - if $C = D \times E$ then $a \cdot \pi_1, a \cdot \pi_2, b \cdot \pi_1, b \cdot \pi_2 \in \mathbf{SN}$ by Property (6), thus $e \cdot \delta(x.a \cdot \pi_1, y.b \cdot \pi_1) \in \mathbf{SN}$ and $e \cdot \delta(x.a \cdot \pi_2, y.b \cdot \pi_2) \in \mathbf{SN}$ by side IH on D and E , respectively.
Hence $(e \cdot \delta(x.a \cdot \pi_1, y.b \cdot \pi_1), e \cdot \delta(x.a \cdot \pi_2, y.b \cdot \pi_2)) \in \mathbf{SN}$ by (p) , then $e \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by (δ_\times) .
 - if $C = D \rightarrow E$, let $w : D$ be a variable such that $w \notin \{x, y\} \cup \text{FV}(a) \cup \text{FV}(b) \cup \text{FV}(e)$. Then $a \cdot w \in \mathbf{SN}$ and $b \cdot w \in \mathbf{SN}$ by Property (T2), thus $e \cdot \delta(x.a \cdot w, y.b \cdot w) \in \mathbf{SN}$ by side IH on D .
Hence $\lambda w : C \cdot e \cdot \delta(x.a \cdot w, y.b \cdot w) \in \mathbf{SN}$ by (λ) , then $e \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by (δ_\rightarrow) , concluding the side induction. →

SN and term formation

→ Proof. (vi)

- $e = z \vec{R} \delta(u.f, v.g)$ by (V_2) , so $z \vec{R} \in \mathbf{SN}$, $f : T \in \mathbf{SN}$, and $g : T \in \mathbf{SN}$. Thus $f \cdot \delta(x.a, y.b) \in \mathbf{SN}$ and $g \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by IH on f and g .
Then $z \vec{R} \delta(u.f \cdot \delta(x.a, y.b), v.g \cdot \delta(x.a, y.b)) \in \mathbf{SN}$ by (V_1) , hence $e \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by (δ_+) .
- $e = \text{inl}_A c$ by (i_1) , so $c \in \mathbf{SN}$. Since $e : T = A + B$ and $c : A$, $a[x/e] \in \mathbf{SN}$ by IH on A . Hence $e \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by (δ_1) .
The case $e = \text{inr}_B c$ by (i_2) is symmetrical.
- $e = (\lambda w : C d) c \vec{D}$ by (β) , so $d[w/c] \vec{D} \in \mathbf{SN}$ and $c \in \mathbf{SN}$. Since $e : T$, also $d[w/c] \vec{D} : T$, thus $d[w/c] \vec{D} \delta(x.a, y.b) \in \mathbf{SN}$ by IH. Hence $e \cdot \delta(x.a, y.b) \in \mathbf{SN}$ by (β) .

The cases for the rules (π_1) , (π_2) , (δ_1) , (δ_2) , (δ_\times) , (δ_\rightarrow) , (δ_+) , (ϕ_\times) , (ϕ_\rightarrow) , and (ϕ_+) are analogous.

→

SN and term formation

→ Proof. (vii)

Property (9) is similar, but additional care has to be taken when the variable to substitute is x in $x\vec{R}$. It has to be shown that $e[x/a] \in \mathbf{SN}$ from $e, a \in \mathbf{SN}$.

- $e = w\vec{R}$ by (V_1) , so $r[x/a] \in \mathbf{SN}$ by IH on each term $r \in \vec{R}$.

If $x \neq w$ then $e[x/a] = w(\vec{R}[x/a]) \in \mathbf{SN}$ by (V_1) .

Thus assume $x = w$. Then $(x\vec{R})[x/a] \in \mathbf{SN}$ by side induction on $|\vec{R}|$: if \vec{R} is empty then $(x\vec{R})[x/a] = a \in \mathbf{SN}$ by hypothesis. Otherwise $\vec{R} = \vec{S}G$ and $(x\vec{S})[x/a] \in \mathbf{SN}$ by side IH.

If $G = \pi_1$ or $G = \pi_2$ then $(x\vec{R})[x/a] = (x\vec{S})[x/a] \cdot G \in \mathbf{SN}$ by Property (6).

Otherwise $G:B$ is a term. Let $z:B$ be a variable such that $z \notin \text{FV}(a) \cup \text{FV}(x\vec{R})$. Then $(x\vec{R})[x/a] = ((x\vec{S})[x/a] \cdot z)[z/G[x/a]]$.

Since $(x\vec{S})[x/a] \cdot z \in \mathbf{SN}$ by Property (T2), $G[x/a] \in \mathbf{SN}$ as already seen, and B is a proper subtype of T , then $(x\vec{R})[x/a] \in \mathbf{SN}$ by IH. →

SN and term formation

→ Proof. (viii)

- $e = w \vec{R} \delta(y.b, z.c)$ by (V_2) , so $(w \vec{R})[x/a] \in \mathbf{SN}$, $b[x/a] \in \mathbf{SN}$, and $c[x/a] \in \mathbf{SN}$ by IH. It is safe to assume $y, z \notin \{x\} \cup \text{FV}(a)$.

If $x \neq w$ then $e[x/a] = (w \vec{R})[x/a] \cdot \delta(y.b[x/a], z.c[x/a]) \in \mathbf{SN}$ by (V_2) .

Thus assume $x = w$ and let $x \vec{R} : B + C$. If \vec{R} is inhabited then $B + C$ is a proper subtype of T , the type of a and x . Hence

$$e[x/a] = ((x \vec{R})[x/a]) \cdot \delta(y.b[x/a], z.c[x/a]) \in \mathbf{SN}$$

by IH on $B + C$.

→

SN and term formation

↪ Proof. (ix)

Therefore, let \vec{R} be empty, so $e[x/a] = a \cdot \delta(y.b[x/a], z.c[x/a])$ whose type is atomic or a sum. Then $e[x/a] \in \mathbf{SN}$ is proved by showing that $a \in \mathbf{SN}$ implies $a \cdot \delta(y.b[x/a], z.c[x/a])$ by side induction on the generation of $a \in \mathbf{SN}$:

- $a = u \vec{S} \in \mathbf{SN}$ by (V_1) . Then $e[x/a] = u \vec{S} \cdot \delta(y.b[x/a], z.c[x/a]) \in \mathbf{SN}$ by (V_2) since its type is atomic or a sum.
- $a = u \vec{S} \delta(v_1.f, v_2.g)$ by (V_2) , so $u \vec{S}, f, g \in \mathbf{SN}$. Thus

$$f \cdot \delta(y.b[x/a], z.c[x/a]) \in \mathbf{SN}$$

$$g \cdot \delta(y.b[x/a], z.c[x/a]) \in \mathbf{SN}$$

by side IH on f and g . Then

$$u \vec{S} \delta(v_1.f \cdot \delta(y.b[x/a], z.c[x/a]), \\ v_2.g \cdot \delta(y.b[x/a], z.c[x/a])) \in \mathbf{SN}$$

by (V_2) , hence $e[x/a] \in \mathbf{SN}$ by (δ_+) .

↪

SN and term formation

→ Proof. (x)

- $a = \text{inl}_C a'$ by (i_1) , so $a' : B \in \mathbf{SN}$. Since $T = B + C$, $(b[x/a])[y/a'] \in \mathbf{SN}$ by main IH on B . Hence $e[x/a] \in \mathbf{SN}$ by (δ_1) .
The case $a = \text{inr}_B a'$ by (i_2) is symmetrical.
- $a = (\lambda u : E f) g \vec{D}$ by (β) , so $f[u/g] \vec{D} \in \mathbf{SN}$ and $g \in \mathbf{SN}$. Thus

$$f[u/g] \vec{D} \cdot \delta(y. b[x/a], z. c[x/a]) \in \mathbf{SN}$$

by side IH on $f[u/g] \vec{D}$. Hence $e[x/a] \in \mathbf{SN}$ by (β) .

The cases for all the other suitable rules, (π_1) , (π_2) , (δ_1) , (δ_2) , (δ_\times) , (δ_\rightarrow) , (δ_+) , and (ϕ_+) , are analogous. This concludes the (V_2) case. →

SN and term formation

→ Proof. (xi)

- $e = \lambda y : B b$ by (λ) , so $b \in \mathbf{SN}$. It is safe to assume $y \notin \{x\} \cup \text{FV}(a)$.
Thus $b[x/a] \in \mathbf{SN}$ by IH on b . Hence $e[x/a] = \lambda y : B b[x/a] \in \mathbf{SN}$ by (λ) .
The cases for the rules (p) , (i_1) , (i_2) , and (ϕ_a) are analogous.
- $e = (\lambda y : B c) b \vec{D}$ by (β) , so $c[y/b] \vec{D} \in \mathbf{SN}$ and $b \in \mathbf{SN}$. It is safe to assume $y \notin \{x\} \cup \text{FV}(a)$. Then $(c[y/b] \vec{D})[x/a] \in \mathbf{SN}$ and $b[x/a] \in \mathbf{SN}$ by IH. Since

$$\begin{aligned} & (c[y/b] \vec{D})[x/a] \\ &= (c[y/b][x/a])(\vec{D}[x/a]) \\ &= ((c[x/a])[y/b[x/a]])(\vec{D}[x/a]) , \end{aligned}$$

$e[x/a] = (\lambda y : B c[x/a])(b[x/a])(\vec{D}[x/a]) \in \mathbf{SN}$ by (β) .

The cases for the rules (δ_1) and (δ_2) are analogous.

→

SN and term formation

↪ Proof. (xii)

- $e = (b, c) \pi_1 \vec{D}$ by (π_1) , so $b \vec{D} \in \mathbf{SN}$ and $c \in \mathbf{SN}$. Then
 $(b \vec{D})[x/a] = (b[x/a])(\vec{D}[x/a]) \in \mathbf{SN}$ and $c[x/a] \in \mathbf{SN}$ by IH.
Hence $(b[x/a], c[x/a]) \pi_1 (\vec{D}[x/a]) = e[x/a] \in \mathbf{SN}$ by (π_1) .

The cases for the rules (π_2) , (ϕ_{\times}) , (ϕ_{\rightarrow}) , and (ϕ_{+}) are similar.

↪

SN and term formation

→ Proof. (xiii)

■ $e = b \cdot \delta(y.c, z.d) \vec{D}$ by (δ_{\times}) , so

$$(b \cdot \delta(y.c \cdot \pi_1, z.d \cdot \pi_1), b \cdot \delta(y.c \cdot \pi_2, z.d \cdot \pi_2)) \vec{D} \in \mathbf{SN} .$$

It is safe to assume $y, z \notin \{x\} \cup \text{FV}(a)$. Thus, by IH,

$$\begin{aligned} & \left((b \cdot \delta(y.c \cdot \pi_1, z.d \cdot \pi_1), b \cdot \delta(y.c \cdot \pi_2, z.d \cdot \pi_2)) \vec{D} \right) [x/a] \\ &= (b[x/a] \cdot \delta(y.c[x/a] \cdot \pi_1, z.d[x/a] \cdot \pi_1), \\ & \quad b[x/a] \cdot \delta(y.c[x/a] \cdot \pi_2, z.d[x/a] \cdot \pi_2)) (\vec{D}[x/a]) \in \mathbf{SN} . \end{aligned}$$

Hence $b[x/a] \cdot \delta(y.c[x/a], z.d[x/a]) (\vec{D}[x/a]) = e[x/a] \in \mathbf{SN}$ by (δ_{\times}) .

The cases for the rules (δ_{\rightarrow}) and (δ_{+}) are analogous. □

References

This proof follows the general guidelines of F. Joachimski and R. Matthes, *Short Proofs of Normalization*, Archive for Mathematical Logic 42, 59–87 (2003).

The main differences are

- slightly more general permutation rules
- \perp (**0** type) and \wedge (\times type constructor) have also been considered
- all the uniqueness rules have been included in the proof
- a mistake in the published proof, which has been later corrected by the authors, is avoided by an alternative proof pattern
- the proof has the same general structure, but many local aspects use different approaches, e.g., the combinatorics of permutations via Δ and ∇
- more details (!!!)

The end

